Large Deviations for Randomly Weighted Sum of Random Measures

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Problem

Let $\mathcal{Z}_n, n = 1, 2, ...$ be sequence of i.i.d. random probability measures on space S with common law Π , and, independently, let $\mathbf{W} = \{W_i : i \ge 1\}$ be i.i.d. positive random variables.

Set

$$X_{nk} = \frac{W_k}{\sum_{i=1}^n W_i}, n \ge 1$$

and

$$\mathcal{W}_n(\Pi, \mathbf{W}) = \sum_{k=1}^n X_{nk} \mathcal{Z}_k$$

Assume that

- 1 S is compact Polish space.
- 2 The mean measure of Π is ν_0 .

$$3 \lim_{n \to \infty} \mathbb{E}\left[\sum_{k=1}^{n} X_{nk}^{2}\right] = 0$$

Then

 $\mathcal{W}_n(\Pi, \mathbf{W}) \to \nu_0$ in probability as $n \to \infty$.

Problem: Large deviation principle for $\{W_n(\Pi, \mathbf{W}) : n \ge 1\}$.

Example 1(Empirical Distribution)

$$\mathcal{L}_{n,\nu_0} = \frac{1}{n} \sum_{k=1}^n \delta_{\xi_k}$$

where $\xi_k, k = 1, 2, ...$ are i.i.d. with common distribution ν_0 .

Example 2(Finite Dirichlet Weight)

$$\mathcal{W}_{n,\nu_0} = \sum_{k=1}^n \frac{W_k}{\sum_{i=1}^n W_i} \delta_{\xi_k}$$

where $W_i, i = 1, 2, ...$ are i.i.d. exponential with parameter one, $\xi_k, k = 1, 2, ...$ are i.i.d. with common distribution ν_0 .

Example 3(Dirichlet Process)

For each $n \ge 1$, let $\{J_i : i \ge 1\}$ denote the set of jump sizes of a gamma subordinator over the interval [0, n]. For $1 \le k \le n$, the set $\{J_{ki} : i \ge 1\}$ consists of all jump sizes over [k-1, k]. The sequence $\xi_k, k = 1, 2, ...$ is i.i.d. with common distribution ν_0 .

$$\mathcal{V}_{n,\nu_0} = \sum_{k=1}^{\infty} \frac{J_k}{\sum_{i=1}^{\infty} J_i} \delta_{\xi_k}$$
$$= \sum_{k=1}^n \frac{\sum_{i=1}^{\infty} J_{ki}}{\sum_{i=1}^{\infty} J_i} \sum_{l=1}^{\infty} \frac{J_{kl}}{\sum_{i=1}^{\infty} J_{ki}} \delta_{\xi_l}$$
$$= \sum_{k=1}^n \frac{\sum_{i=1}^{\infty} J_{ki}}{\sum_{i=1}^{\infty} J_i} \mathcal{Z}_k$$

where $\mathcal{Z}_1, \ldots, \mathcal{Z}_n$ are i.i.d. with the same distribution as \mathcal{V}_{1,ν_0} .

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Motivation

Bayesian Basics: Consider a random variable ξ with distribution depending on parameter θ . In Bayesian statistics, the parameter is modelled as a random variable Θ . This reflects the basic principle of Bayesian statistics: all forms of uncertainty should be expressed as randomness.

The distribution Q of Θ is called the *prior distribution*.

Under a Bayesian model, data is generated in two stages, as

 $\Theta \sim Q$ $\xi_1, \xi_2, \dots |\Theta \sim \text{iid with common distribution } P_{\Theta}.$

Here the sequence ξ_1, ξ_2, \ldots is conditionally i.i.d. or exchangeable.

The main objective is then to determine the *posterior distribution*, the

conditional distribution of Θ given the data,

$$Q\{\Theta \in \cdot | \xi_i, i = 1, \dots, n\}.$$

This corresponds to parameter estimation in the classical approach.

A *Bayesian nonparametric model* is a Bayesian model with infinite dimensional parametric space.

Examples include the space of probability measures and the space of probability density functions.

Let Θ follow the **Dirichlet process** with base measure ν_0 and concentration parameter β . Then the posterior distribution of Θ given the sample ξ_1, \ldots, ξ_n is

$$U\mathcal{V}_{\beta,\nu_0} + (1-U)\sum_{k=1}^n X_{nk}\delta_{\xi_k}$$

where U is $Beta(\beta, n)$, W_1, \ldots, W_n i.i.d. exponential(1), and

$$X_{nk} = \frac{W_k}{\sum_{i=1}^n W_i}$$

lf

$$\frac{1}{n}\sum_{i=1}^n \delta_{\xi_i} \to \nu_0,$$

then

$$U\mathcal{V}_{\beta,\nu_0} + (1-U)\sum_{k=1}^n X_{nk}\delta_{\xi_k} \to \nu_0.$$

The corresponding large deviation principle is shown in **Ganesh and O'Connell** [5] to have rate function $H(\nu_0|\mu)$.

Our large deviation result can thus be viewed as the annealed large deviation associated with the Dirichlet posterior.

Result

Theorem 1. (F. [2])Large deviation principle for $\{W_n(\Pi, \mathbf{W}) : n \ge 1\}$ holds if some local estimates hold for projections on a large class of partitions.

Remark 1. The *i.i.d.* assumption for $\{Z_n : n \ge 1\}$ can be relaxed. But the local estimates will be difficult to obtain. A successful situation is found in **Gamboa** and **Rouault** [3] and **Gamboa, Nagel and Rouault** [4] where $\{Z_n : n \ge 1\}$ are the Dirac measures of eigenvalues of random matrices.

Theorem 2. (F. [2]) Large deviation principle for $\{W_{n,\nu_0} : n \ge 1\}$ holds with rate function

$$J(\mu, \nu_0) = \inf\{H(\nu|\mu) + H(\nu|\nu_0) : \nu \in M_1(S)\}.$$

Comparison of Rate Functions

1 Rate function for empirical distribution or Sanov's theorem (Sanov [10]): $H(\mu|\nu_0)$ corresponding to

$$\mathcal{L}_{n,\nu_0} \to \nu_0$$

2 Rate function for Dirichlet process (Lynch and Sethuraman [7], Dawson and F. [1]): $H(\nu_0|\mu)$ corresponding to

$$\mathcal{V}_{n,\nu_0} \to \nu_0$$

3 Rate function for the finite Dirichlet weighted sum: $J(\mu, \nu_0)$ corresponding to

$$\mathcal{W}_{n,\nu_0} \to \nu_0$$

Inequality

 $J(\mu, \nu_0) \le \min\{H(\mu|\nu_0), H(\nu_0|\mu)\}$

- The inequality can be strict!
- \mathcal{W}_{n,ν_0} is more "random" and "far from ν_0 " than both \mathcal{L}_{n,ν_0} and \mathcal{V}_{n,ν_0}

Application

Random Means and LDP

Given a random probability of the form

$$\sum_{i=1}^{\infty} P_i \delta_{X_i},$$

 ∞

i=1

the random mean is

The comprehensive coverages on random means can be found in Lijoi and Prünster [6] and Pitman [8].

 $\sum^{n} X_i P_i.$

Sample and Dirichlet Means

Sample Mean

$$M_n^1 = \langle \mathcal{L}_{n,\nu_0}, x \rangle = \frac{1}{n} \sum_{i=1}^n \xi_i$$

Finte Dirichlet Mean

$$M_n^2 = \langle \mathcal{W}_{n,\nu_0}, x \rangle = \sum_{i=1}^n \frac{W_i}{\sum_{k=1}^n W_k} \xi_i$$

Dirichlet Mean

$$M_n^3 = \langle \mathcal{V}_{n,\nu_0}, x \rangle = \sum_{i=1}^{\infty} V_i \xi_i$$

where $V_i = (1 - U_1) \dots (1 - U_{i-1})U_i$, U_i is i.i.d. Beta(1, n).

– Typeset by Foil $\mathrm{T}_{\!E\!}\mathrm{X}$ –

LDPs

LDPs hold for $M_n^i, i = 1, 2, 3$ by contraction principle.

Rate Functions

Sample Mean (forward projection)

$$I_1(u, \boldsymbol{\nu_0}) = \inf\{H(\mu|\boldsymbol{\nu_0}) : \langle \mu, x \rangle = u\}$$

Finite Dirichlet Mean

$$I_2(u, \boldsymbol{\nu_0}) = \inf\{J(\mu, \boldsymbol{\nu_0}) : \langle \mu, x \rangle = u\}$$

Dirichlet Mean (reversed projection)

$$I_3(u, \nu_0) = \inf\{H(\nu_0|\mu) : \langle \mu, x \rangle = u\}$$

Relations

In general, we have

 $I_2(u, \nu_0) \le \min\{I_1(u, \nu_0), I_3(u, \nu_0)\}.$

If $\nu_0(dx) = dx$, then

$$I_1(u, \nu_0) = I_3(u, \nu_0)$$

= $I_2(u, \nu_1)$

where (see Regazzini, Guglielmi, and Di Nunno [9])

$$\begin{array}{lll}
\nu_{1} &= & \text{law of } M_{1}^{3} = \langle \mathcal{V}_{1,\nu_{0}}, x \rangle \\
\frac{d \,\nu_{1}}{d \,\nu_{0}} &= & \frac{1}{\pi} e^{-\int_{0}^{1} \log |x-y| d \, y} \sin(\pi x).
\end{array}$$

The density of the law of M_n^3 has Radon-Nikodym derivative with respect to u_0

$$\frac{n-1}{\pi} \int_0^x (x-y)^{n-2} e^{-n \int_0^1 \log |y-z| dz} \sin(n\pi y) dy, n \ge 2, 0 < x < 1.$$

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Thank You!